ON LINEAR ESTIMATION AND TESTING OF HYPOTHESIS

The object of the present note is to consider the most general problem in the theory of linear estimation and get suitable generalisations of Markoff's theorem and to derive suitable tests of significance connected with estimated functions.

2. There are a stochastic variates $T_1, T_2, ...$ T_n with the variance and covariance matrix $\Lambda \sim ((\lambda_k))$ such that

$$E(T_1) = \theta_1 = \alpha_{11} r_1 + \alpha_{12} r_2 + \dots + \alpha_{1m} r_m$$
 (2.1)

and m not necessarily less than n. Some of the r's may be regression constants in which case their coefficients will be functions of concomitant variates. We want a linear function $L(T) \sim b_1T, \ b_2T_1 + \dots + b_nT_n$, such that $E\{LT\} = \theta = l_1r_1 + l_2r_2 + \dots + l_nT_n$, a given parametric function and $V\{L(T)\}$ is minimum. If L(T) can be found to possess such properties then it is called the best estimate of θ .

3. It has been shown that the set of equa-

$$Q_{i} = L_{i} \Lambda^{-1} y' = \sum_{i=1}^{n} L_{i} \Lambda^{-1} L_{i}' r_{i} = h_{i}$$
 (3.1)

 $(i = 1, 2, \dots m)$, where L_i and y are the row matrices $(a_{1i}, a_{2i_1}, \dots a_{ni})$ and $(T_1, T_2, \dots T_n)$ and the dash represents their transpose obtained by minimising

$$L = \Sigma \Sigma \lambda^{ij} (T_i - \theta_i) (T_j - \theta_j), \qquad (3.2)$$

where λ^{ij} are the elements of Λ^{-1} , are such that Q_i is the best estimate of h_i and the best estimate of θ is given by $\Sigma \in Q_i$ where C's are such that $\theta = \Sigma \in A_i$. If the rank of the matrix of the equations (3.1) is less than m_i , then all parametric functions are not estimable

4. The set of equations (3.1) possesses the following properties.

- (i) Variance of Q_i is the coefficient of r in the ith equation;
- (ii) Covariance of Q_i and Q_j is the coefficient of r_i in the ith equation;
- (iii) If Σ c, $Q_i \equiv 0$, then the parametric
- function \(\Sigma c_{i, r_i}\) is not estimable:

 ((v) If \(\Sigma a_i \) Q_i and \(\Sigma b_i \) Q_i are the estimates

 of \(\Sigma l_{i, r_i}\) and \(\Sigma m_{i, r_i}\), then their variances and covariances are given by

$$\begin{pmatrix} \Sigma & ai & \Sigma & bi \\ \Sigma & am & \Sigma & bm \end{pmatrix}$$

- (v) The number of estimable parametric functions is equal to the number of functionally independent Q's.
- (vi) An intrinsic property is that all the above five properties hold good even with a subset of the equations obtained by eliminating one or more r's.
- (vii) The best estimate of any estimable parametric function Σ l r is unique and is obtained by substituting any particular solution for r's obtained by solving the equations (3-1) or any set of equations derived from it; and so also the expressions for the variances and covariances.
- 5. If we want to test the hypothesis $\Sigma l_r = t$ then we construct the statistic

$$\omega = \frac{\Sigma c Q - \xi}{V \Sigma c l},$$

where $\Sigma \in Q$ is the estimate of $\Sigma \mid r$ and refer the normal tables for tests of significance. If we want to test the composite hypothesis $\partial_t = \Sigma \mid_{QT_p} = \{t, t = 1, 2, \dots k \text{ we take a linear}$ compound of these k relations

with the corresponding estimate

$$\Sigma \lambda_i (\Sigma c_i, Q_i - t_i) = \Sigma \lambda_i P_i$$

and variance $\Sigma \Sigma \lambda_i \lambda_j V_{ij}$ where $V_{ij} = cov (P_i P_j)$ and construct the above statistic

$$V = \frac{\sum \lambda_i}{\sqrt{\sum \sum \lambda_i}} \frac{P_i}{\lambda_i} \frac{V_{ij}}{V_{ij}}$$

We choose the compounding coefficients such that V^2 is maximun. This leads to the determinental equation

$$|P_{i}P_{i}-V^{e}V_{ij}|=0.$$

The distribution of $V\tilde{\epsilon}$ on the non-null hypothesis is obtained as

on the assumption that the y's form a multivariate normal system. The necessary statistics, when the variances and co-variances are not known are obtained by studentising the above statistics. Some of the important distributions will be discussed in a paper to be published in full clsewhere.

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