

ON A CLASS OF ADMISSIBLE ESTIMATORS OF THE NORMAL VARIANCE

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1. INTRODUCTION

Let X_1, X_2, \dots, X_n be a set of independent normal variables with mean m and variance v . The problem is to make a point estimate $t(x_1, x_2, \dots, x_n)$ of v on the basis of n random observations x_1, x_2, \dots, x_n on the chance variables X_1, X_2, \dots, X_n . Let us first consider the simpler case where the mean m is known. The maximum likelihood estimator of v is S/n where $S = \sum(x_i - m)^2$. The amount of information $I(v)$ per unit of sample is $I(v) = 1/(2v^2)$ and so from the Cramér-Rao inequality we have that for any unbiased estimator t of v

$$E(t-v)^2 \geq \frac{1}{nI(v)} = \frac{2v^2}{n} \quad \dots (1.1)$$

It is easily verified that the maximum likelihood estimator S/n is unbiased and that its variance is $(2v^2)/n$ so that in the class of all unbiased estimators S/n is essentially the only admissible estimator if we take our loss function proportional to the square of the error committed. That is to say if t be any other unbiased estimator of v then, unless of course $t = S/n$ almost everywhere,

$$E(t-v)^2 > E(S/n-v)^2$$

with the strict sign of inequality holding for at least one v (as a matter of fact in this case the strict sign of inequality will hold everywhere).

Now consider the class of estimators aS for all values of a . We note that

$$\begin{aligned} E(aS-v)^2 &= E\{a(S-nv) + (an-1)v\}^2 \\ &= \{2a^2n + (an-1)^2\}v^2 \end{aligned}$$

and that the above is minimum at $a = 1/(n+2)$, the minimum value being

$$E\left(\frac{S}{n+2} - v\right)^2 = \frac{2v^2}{n+2} \quad \dots (1.2)$$

Thus in the class of estimators of the form aS the only admissible one is $S/(n+2)$. The maximum likelihood estimator S/n , which is also the best unbiased estimator, is not admissible in the sense of Wald. It is very surprising that by introducing a bias in our estimator t we can make the risk function $r(v|t) = E(t-v)^2$ uniformly smaller, than the Cramér-Rao limit (1.1). Such a thing, however, is not possible in every case. Take for instance the case of the normal mean m with known variance, say unity. By the Cramér-Rao inequality if t be any unbiased estimator of m then

$$E(t-m)^2 \geq \frac{1}{nI(m)} = \frac{1}{n}.$$

The maximum likelihood estimator Z attains the above limit for all m . It was proved by the author and, under a more general set-up, by Blyth (1951) that in the class of all estimators that generate continuous risk functions the estimator Z is admissible. In the next section we proceed to find out a class of admissible estimators for the variance. Throughout in this paper we take the square of the error as our loss function.

2. A CLASS OF ADMISSIBLE ESTIMATORS

Since $S = \Sigma(x_i - m)^2$ is a sufficient statistic for v we have, from the Rao-Blackwell theorem and the convexity of the loss function, that for the purpose of estimating v we need restrict ourselves to only functions of S . The frequency function $p(S|v)dS$ of S is

$$p(S|v)dS = \frac{1}{2^{n/2} \Gamma(n/2)} v^{-n/2} S^{(n/2)-1} e^{-S/2v} dS$$

$$(0 \leq S < \infty, 0 < v < \infty).$$

Now consider the a-priori probability frequency for v

$$p(v)dv = \frac{\lambda^{\mu-1}}{2^{\mu-1} \Gamma(\mu-1)} v^{-\mu} e^{-\lambda/2v} dv \quad (\lambda > 0, \mu > 1) \quad \dots (2.1)$$

The joint frequency function of S and v becomes

$$p(S, v)dS dv = p(v)p(S|v)dS dv$$

$$= \frac{\lambda^{\mu-1}}{2^{\frac{n}{2} + \mu - 1} \Gamma(\frac{n}{2}) \Gamma(\mu-1)} S^{\frac{n}{2}-1} v^{-\left(\frac{n}{2} + \mu\right)} e^{-\frac{S+\mu}{2v}} dS dv$$

The marginal frequency of S is

$$p(S)dS = dS \int_0^{\infty} p(S, v)dv$$

$$= \frac{\lambda^{\mu-1}}{B\left(\frac{n}{2}, \mu-1\right)} \frac{S^{\frac{n}{2}-1}}{(S+\lambda)^{\frac{n}{2} + \mu - 1}}$$

The a-posteriori frequency function of v , given S , is

$$p(v|S)dv = \frac{p(S, v)dv}{p(S)}$$

$$= \frac{(S+\lambda)^{\frac{n}{2} + \mu - 1}}{2^{\frac{n}{2} + \mu - 1} \Gamma\left(\frac{n}{2} + \mu - 1\right)} v^{-\left(\frac{n}{2} + \mu\right)} e^{-\frac{S+\lambda}{2v}} dv$$

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The a-posteriori expected value of v given S is

$$E(v|s) = \int_0^{\infty} v p(v|S) dv \\ = \frac{S+\lambda}{n+2\mu-4} = t_{\lambda, \mu}(S). \quad \dots (2.2)$$

Now consider the estimator $t_{\lambda, \mu}$. The risk function generated by $t_{\lambda, \mu}$ is

$$r(v|t_{\lambda, \mu}) = E\{(t_{\lambda, \mu} - v)^2 | v\} \\ = \frac{2n+4(\mu-2)^2}{(n+2\mu-4)^2} v^2 - \frac{4\lambda(\mu-2)}{(n+2\mu-4)^2} v + \frac{\lambda^2}{(n+2\mu-4)^2}$$

and the average risk for the a-priori distribution (2.1) is

$$\bar{r}(t_{\lambda, \mu}) = \int_0^{\infty} r(v|t_{\lambda, \mu}) p(v) dv \\ = \frac{\lambda^2}{2(\mu-2)(\mu-3)(n+2\mu-4)} \quad \dots (2.3)$$

It should be noted that (2.3) is defined only when $\mu > 3$ in (2.1) so that we henceforth restrict ourselves to only such a-priori distributions of the form (2.1) for which $\mu > 3$. Thus for every $\lambda > 0$ and $\mu > 3$ the estimator $t_{\lambda, \mu}$ is essentially the only Bayes solution corresponding to the a-priori frequency (2.1) and so every $t_{\lambda, \mu}$ ($\lambda > 0, \mu > 3$) is admissible. We make the interesting observation that although $t_{\lambda, \mu}$ is admissible for every $\lambda > 0$ and $\lambda > 3$ the limiting Bayes solution $t_{0, \mu} = \frac{S}{n+2\mu-4}$ obtained by making $\lambda \rightarrow 0$ is not admissible

for any $\mu > 3$. It is conjectured that the limiting Bayes solution $t_{0, \mu} = \frac{S}{n+2}$ considered in (1.2) is admissible. We also note that there cannot exist any estimator t of v for which the risk function $r(v|t) = E\{(t-v)^2 | v\}$ is a bounded function of v for all v in $0 < v < \infty$. For, if possible, let t^0 be an estimator for which $r(v|t^0) \leq M$ for all v . Then the average risk, with (2.1) as the a-priori weight function for v , will be $\leq M$. But for a sufficiently large λ (and any $\mu > 3$) (2.3) will certainly exceed M which contradicts the fact that $t_{\lambda, \mu}$ is a Bayes solution. Thus it is clear that there cannot exist any minimax estimator for v and that some other criterion has to be set up for choosing a good estimator from the class (2.2) of admissible estimators.

3. THE CASE WHEN THE MEAN IS UNKNOWN

So long we considered the case where the mean m was known. Now consider the case where the mean m also is unknown.

Since \bar{x} and $S = \Sigma(x_i - \bar{x})^2$ jointly contain all the information about the parameter point (m, v) it follows from the Rao-Blackwell Theorem that all admissible estimators are essentially (i.e. excepting for a set of Lebesgue measure zero) functions of only \bar{x} and S . If however, we restrict ourselves to only such estimators t for which

the risk functions $r(m, v|t) = E[(t-v)^2 | m, v]$ are functions of v alone then we can prove the following:

Theorem 3.1: *An admissible estimator for which the associated risk function is independent of m is essentially a function of S alone.*

Proof: Let $t = t(x, S)$ be any admissible estimator such that $r(m, v|t)$ is independent of m . Let $t_1 = t(\bar{x} + \lambda, S)$. Since m is a location parameter it is readily seen that

$$\begin{aligned} r(m, v|t_1) &= E[(t_1 - v)^2 | m, v] \\ &= E[(t - v)^2 | m + \lambda, v] \\ &= r(m + \lambda, v|t) \\ &= r(m, v|t) \end{aligned}$$

since $r(m, v|t)$ is independent of m . Thus t and t_1 generates the same risk function. Hence from the convexity of the loss function $(t-v)^2$ it follows that the estimator $\frac{1}{2}(t+t_1)$ will be uniformly more powerful than t unless $t=t_1$ almost everywhere. Since by assumption t is admissible in the class of those estimators that generate the same risk function for all m it follows that, for each real λ , $t(x, S) = t(\bar{x} + \lambda, S)$ almost everywhere in x, S . And this proves that $t(x, S)$ is essentially a function of S alone.

We can prove in the same way as in the previous section that in the subclass of all those estimators which are essentially functions of S alone all estimators of the form.

$$t_{1,\mu} = \frac{S + \lambda}{n - 1 + 2\mu - 4} \quad (\lambda > 0, \mu > 3) \quad \dots (3.1)$$

are admissible. It is to be noted that we now have $n-1$ and not n degrees of freedom for S and that is why there is a slight difference in the formulae (2.2) and (3.1). We also note that the best unbiased estimator $S/(n-1)$ and the maximum likelihood estimator S/n are both uniformly less powerful than the limiting form of (3.1) namely $t_{\infty} = S/(n-1)$.

We now prove that all estimators of the form (3.1) are admissible in the class of all estimators for which the associated risk functions are continuous. It is conjectured that $t_{1,\mu}$ is admissible in the unrestricted class of all estimators. Consider the a-priori probability density function for the parameter point (m, v) namely

$$\begin{aligned} p(m, v) dm dv &= \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{m^2}{2\sigma^2}} \frac{\lambda^{\mu-1}}{2^{\mu-1}\Gamma(\mu-1)} v^{-\mu} e^{-\frac{\lambda}{2v}} dm dv \\ &-\infty < m < \infty, 0 < v < \infty, \sigma > 0, \lambda > 0, \mu > 3 \end{aligned}$$

As in the previous section we take $\mu > 3$ in order that the average risk associated with the Bayes solution may be finite.

The a-posteriori probability density of (m, v) is

$$p(m, v | x, S) dm dv = \frac{e^{-\frac{m^2}{2\sigma^2}} - \left(\frac{n}{2} + \mu\right) e^{-\frac{T}{2v}}}{\int \int e^{-\frac{m^2}{2\sigma^2}} - \left(\frac{n}{2} + \mu\right) e^{-\frac{T}{2v}} dm dv}$$

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where $T = n(x-m)^2 + S + \lambda$.

Hence the Bayes' solution corresponding to the a-priori density $p(m, v) dm dv$ is

$$\begin{aligned} t_{\lambda, \sigma} &= E(v|z, S) \\ &= \int \int v p(m, v|z, S) dm dv \\ &= \frac{\int_{-\infty}^{\infty} e^{-\frac{m^2}{2\sigma^2}} dm \int_0^{\infty} e^{-\left(\frac{n}{2} + \mu - 1\right) v} e^{-\frac{T}{2v}} dv}{\int_{-\infty}^{\infty} e^{-\frac{m^2}{2\sigma^2}} dm \int_0^{\infty} v^{-\left(\frac{n}{2} + \mu\right)} e^{-\frac{T}{2v}} dv} \\ &= \frac{\int_{-\infty}^{\infty} T^{-\left(\frac{n}{2} + \mu - 2\right)} e^{-\frac{m^2}{2\sigma^2}} dm}{\int_{-\infty}^{\infty} T^{-\left(\frac{n}{2} + \mu - 1\right)} e^{-\frac{m^2}{2\sigma^2}} dm} \\ &= \frac{1}{n+2\mu-4} \end{aligned}$$

As both the numerator and the denominator of the above expression are uniformly convergent for all $\sigma > \delta > 0$ we have

$$\begin{aligned} \lim_{\sigma \rightarrow \infty} t_{\lambda, \sigma} &= \frac{\int_{-\infty}^{\infty} T^{-\left(\frac{n}{2} + \mu - 2\right)} dm}{\int_{-\infty}^{\infty} T^{-\left(\frac{n}{2} + \mu - 1\right)} dm} \\ &= \frac{1}{n+2\mu-4} \\ &= \frac{S + \lambda}{(n-1) + 2\mu - 4} \\ &= t_{\lambda, \infty} \end{aligned}$$

we thus observe that $t_{\lambda, \infty}$ is a limiting Bayes solution. This however does not immediately prove the admissibility of $t_{\lambda, \infty}$. We sketch below the method of proof.

Since $e^{-\frac{m^2}{2\sigma^2}} = 1 - \frac{m^2}{2\sigma^2} e^{-\frac{m^2}{2\sigma^2}} \quad 0 < \theta < 1$

we have

$$t_{\lambda, \sigma} = t_{\lambda, \infty} + \frac{1}{\sigma^2} k(z, S, \sigma) \quad \dots (3.2)$$

where $k(z, S, \sigma)$ remains bounded as $\sigma \rightarrow \infty$.

$$\therefore r(m, v|t_{\lambda, \sigma}) = r(m, v|t_{\lambda, \infty}) + \frac{1}{\sigma^2} h(m, v, \sigma) \quad \dots (3.3)$$

where $h(m, v, \sigma)$ remains bounded as $\sigma \rightarrow \infty$.

Hence, with $p(m, v) dm dv$ as the a-priori density, the average risk for $t_{\lambda, \sigma}$ and t_{λ} satisfy the following relationship

$$R(t_{\lambda, \sigma}) = R(t_{\lambda}) - \frac{1}{\sigma^2} g(\sigma) \quad \dots (3.4)$$

where $g(\sigma)$ remains bounded and non-negative as $\sigma \rightarrow \infty$. We omit the detailed discussions regarding convergence that are necessary in (3.2), (3.3), and (3.4).

We now prove that if there exists an estimator t for which

$$r(m, v|t) < r(m, v|t_{\lambda, \sigma})$$

for all m and v then the set of points where the strict sign of inequality holds must be a set of Lebesgue measure zero.

Let A be the set of points where

$$r(m, v|t) < r(m, v|t_{\lambda, \sigma})$$

If $m(A) > 0$ then we can find a sub-set A_1 of A with positive Lebesgue measure and an $\epsilon > 0$ such that for all (m, v) in A_1

$$r(m, v|t) < r(m, v|t_{\lambda, \sigma}) - \epsilon.$$

Then

$$R(t) = \iint r(m, v|t) p(m, v) dm dv < R(t_{\lambda, \sigma}) - \epsilon \iint_{A_1} p(m, v) dm dv.$$

Since $m(A_1) > 0$ it can be easily seen that

$$\sigma \iint_{A_1} p(m, v) dm dv \rightarrow \frac{1}{\sqrt{2\pi}} \int_{A_1} p(v) dv > 0 \text{ as } \sigma \rightarrow \infty$$

where $p(v)dv$ is the marginal a-priori probability density for v .

Thus we have

$$R(t) < R(t_{\lambda, \sigma}) - \frac{1}{\sigma} f(\sigma) \quad \dots (3.5)$$

where $f(\sigma) \rightarrow$ a positive constant as $\sigma \rightarrow \infty$. Form (3.4) and (3.5) we have that for all sufficiently large σ

$$R(t) < R(t_{\lambda, \sigma})$$

which is a contradiction since $t_{\lambda, \sigma}$ is the Bayes solution corresponding to the a-priori probability density $p(m, v) dm dv$.

Hence if t generates a continuous risk function and if $r(m, v|t) < r(m, v|t_{\lambda, \sigma})$ for all m and v then the sign of equality must hold everywhere for if $r(m, v|t) < r(m, v|t_{\lambda, \sigma})$ for at least one (m, v) then, from the continuity of the two risk functions, the strict sign of inequality must hold in a set of positive Lebesgue measure which, as just demonstrated, is a contradiction.

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