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Consistent estimation of density-weighted average derivative by orthogonal series method

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Abstract

The problem of estimation of density-weighted average derivative is of interest in econometric problems, especially in the context of estimation of coefficients in index models. Here we propose a consistent estimator based on the orthogonal series method. Earlier work on this problem dealt with kernel method of estimation.

Keywords: Nonparametric estimation of density-weighted average derivative; Orthogonal series method; Consistency

1. Introduction

In a series of papers, Stoker (1986, 1989), Powell et al. (1989) and Hardle and Stoker (1989) proposed the problem of estimation of the density-weighted average derivative of a regression function.

Let (X_i, Y_i) , $1 \le i \le n$ be i.i.d. bivariate random vectors distributed as (X, Y). Suppose E(Y|X) = g(X) exists and X is distributed with density f. The density-weighted average derivative is defined as

$$\delta = E \left[f(X) \frac{\mathrm{d}g}{\mathrm{d}X} \right]$$

assuming that $q(\cdot)$ is differentiable.

Stoker (1986) and Powell et al. (1989) explain the motivation behind the estimation of density-weighted average derivative. For instance, weighted average derivatives are of practical interest as they are proportional to coefficients in index models. If the model indicates that $g(x) = \alpha + \beta x$, then

$$\frac{\mathrm{d}g}{\mathrm{d}x} = \beta$$

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and $\delta = \beta E[f(X)]$. In general, if $g(x) = F(\alpha + \beta x)$, then

$$\frac{\mathrm{d}g}{\mathrm{d}x} = F'(\alpha + \beta x)\beta$$

and $\delta = E[F'(\alpha + \beta X)f(X)]\beta$.

Kernel method of estimation has been proposed and its properties are investigated in Powell et al. (1989). Here we propose an alternate method for estimation of δ by the method of orthogonal series. The method of orthogonal series for the estimation of density and the regression function has been extensively discussed in Prakasa Rao (1983).

Note that

$$\delta = E \left[f(X) \frac{\mathrm{d}g}{\mathrm{d}X} \right] = \int_{-\infty}^{\infty} f^2(x) \frac{\mathrm{d}g}{\mathrm{d}x} \mathrm{d}x$$
$$= \left[g(x) f^2(x) \right]_{-\infty}^{\infty} - 2 \int_{-\infty}^{\infty} f(x) \frac{\mathrm{d}f}{\mathrm{d}x} g(x) \, \mathrm{d}x$$

integrating by parts.

We assume that the density f(x) and the regression function g(x) satisfy the following conditions:

(A1)
$$\lim_{x \to +\infty} g(x) f^2(x) = 0;$$

(A2) the density function f has an orthogonal series expansion

(i)
$$f(x) = \sum_{l=1}^{\infty} a_l e_l(x),$$

with respect to an orthonormal basis $\{e_l(x)\}$; the function f(x) and the elements of the basis $\{e_l(x)\}$ are differentiable such that

(ii)
$$E \left| \sum_{l=1}^{q(N)} a_l e'_l(X) - f'(X) \right|^2 \to 0 \text{ as } N \to \infty$$

whenever $q(N) \to \infty$; and

(iii)
$$\sup_{l} |e_{l}(x)| < \infty$$
 and $\sup_{l} |e'_{l}(x)| < \infty$.

Assumption (A1) implies that

$$\delta = E \left[f(X) \frac{\mathrm{d}g}{\mathrm{d}X} \right] = -2E \left[g(X) \frac{\mathrm{d}f}{\mathrm{d}X} \right]$$

$$= -2E \left[Y \frac{\mathrm{d}f}{\mathrm{d}X} \right], \tag{1.1}$$

since q(X) = E[Y|X]. Hereafter we write f'(x) for df/dx and in general prime denotes differentiation.

2. Consistency of the estimator

Given a sample of independent and identically distributed observations (X_i, Y_i) , $1 \le i \le n$, a natural estimator of δ is

$$\hat{\delta}_N = \frac{-2}{N} \sum_{i=1}^N Y_i \frac{\mathrm{d}\hat{f}_{Ni}}{\mathrm{d}X} \bigg|_{X = X_i}$$
(2.1)

from (1.1). Here \hat{f}_{Ni} is an estimator of f based on the sample (X_j, Y_j) , $1 \le j \le N$. It is convenient to choose \hat{f}_{Ni} based on (X_j, Y_j) , $1 \le j \le N$, $j \ne i$ and we will do the same in the sequel. An orthogonal series estimator of f is

$$\hat{f}_N(x) = \sum_{l=1}^{q(N)} \hat{a}_{lN}^{(i)} e_l(x)$$

where

$$\hat{a}_{lN}^{(i)} = \frac{1}{N-1} \sum_{\substack{j=1 \ i \neq i}}^{N} e_l(X_j)$$

and $q(N) \to \infty$ as $N \to \infty$ to be chosen at a later stage. Then

$$\hat{\delta}_N = \frac{-2}{N} \sum_{i=1}^N Y_i \left[\sum_{l=1}^{q(N)} \hat{a}_{lN}^{(i)} e_l'(X_i) \right]. \tag{2.2}$$

Let $X_N^{(i)}$ denote the vector $(X_1, \ldots, X_{i-1}, X_{i+1}, \ldots, X_N)$. Hence,

$$\hat{\delta}_{N} = -\frac{2}{N} \sum_{i=1}^{N} \sum_{l=1}^{q(N)} Y_{i} e'_{l}(X_{i}) \hat{a}_{lN}^{(i)}$$

$$= -\frac{2}{N} \sum_{l=1}^{q(N)} \sum_{i=1}^{N} \psi_{l}(X_{i}, Y_{i}) \eta_{l}(X_{N}^{(i)}), \qquad (2.3)$$

where

$$\psi_i(X_i, Y_i) = Y_i e_i'(X_i) \tag{2.4}$$

and

$$\eta_l(X_N^{(i)}) = \hat{a}_{lN}^{(i)}. \tag{2.5}$$

Note that $\eta_l(X_N^{(i)})$ does not depend on the observation X_i by construction. Therefore,

$$E[\hat{\delta}_{N}] = -\frac{2}{N} \sum_{l=1}^{q(N)} \sum_{i=1}^{N} E\{\psi_{l}(X_{i}, Y_{i})\} E\{\eta_{l}(X_{N}^{(i)})\}$$

$$= -2 \sum_{l=1}^{q(N)} E[\psi_{l}(X_{1}, Y_{1})] E[e_{l}(X_{1})]$$

$$= -2 \sum_{l=1}^{q(N)} a_{l} E[Ye'_{l}(X)] \quad \text{(since } E[e_{l}(X_{1})] = a_{l})$$

$$= -2 E\left[Y \sum_{l=1}^{q(N)} a_{l}e'_{l}(X)\right]$$
(2.6)

and

$$E(\hat{\delta}_N) \to -2E \left[Y \frac{\mathrm{d}f}{\mathrm{d}X} \right] = \delta \quad \text{as } N \to \infty$$
 (2.7)

under the assumptions (A2) (ii) and $EY^2 < \infty$. Note that

$$\operatorname{Var}[\hat{\delta}_{N}] = \frac{4}{N^{2}} \sum_{l=1}^{q(N)} \sum_{m=1}^{q(N)} \sum_{i=1}^{N} \sum_{j=1}^{N} \operatorname{Cov}[\psi_{l}(X_{i}, Y_{i}) \eta_{l}(X_{N}^{(i)}), \psi_{m}(X_{j}, Y_{j}) \eta_{m}(X_{N}^{(j)})]$$
(2.8)

Case (i): $i \neq j$. Let us compute

$$cov[\psi_{l}(X_{i}, Y_{i})\eta_{l}(X_{N}^{(i)}), \psi_{m}(X_{j}, Y_{j})\eta_{m}(X_{N}^{(j)})] = E[\psi_{l}(X_{i}, Y_{i})\psi_{m}(X_{j}, Y_{j})\eta_{l}(X_{N}^{(i)})\eta_{m}(X_{N}^{(j)})]
- E[\psi_{l}(X_{i}, Y_{i})\eta_{l}(X_{N}^{(i)})] E[\psi_{m}(X_{j}, Y_{j})\eta_{m}(X_{N}^{(j)})].$$
(2.9)

Observe that

$$E[\psi_{l}(X_{i}, Y_{i})\eta_{l}(X_{N}^{(i)})] = E[\psi_{l}(X_{1}, Y_{1})\eta_{l}(X_{N}^{(1)})]$$

$$= E[Y_{1}e'_{l}(X_{1})]E[\eta_{l}(X_{N}^{(1)})]$$

$$= E[a_{l}Y_{1}e'_{l}(X_{1})]. \tag{2.10}$$

Let

$$I_{1} = E[\psi_{l}(X_{1}, Y_{1})\psi_{m}(X_{2}, Y_{2})\eta_{l}(X_{N}^{(1)})\eta_{m}(X_{N}^{(2)})]$$

$$= E\{\psi_{l}(X_{1}, Y_{1})\psi_{m}(X_{2}, Y_{2})E[\eta_{l}(X_{N}^{(1)})\eta_{m}(X_{N}^{(2)})|(X_{i}, Y_{i}), i = 1, 2]\}$$

$$= E\{\psi_{l}(X_{1}, Y_{1})\psi_{m}(X_{2}, Y_{2})\frac{1}{(N-1)^{2}}E\left[\left(\sum_{\substack{j=1\\j\neq 1}}^{N}e_{l}(X_{j})\right)\left(\sum_{\substack{K=1\\K\neq 2}}^{N}e_{m}(X_{l})\right)|(X_{i}, Y_{i}), i = 1, 2\right]\}.$$

$$(2.11)$$

Note that

$$\left[e_{l}(X_{2}) + \sum_{j=3}^{N} e_{l}(X_{j})\right] \left[e_{m}(X_{1}) + \sum_{k=3}^{N} e_{m}(X_{k})\right] = e_{l}(X_{2}) e_{m}(X_{1}) + e_{m}(X_{1}) \sum_{j=3}^{N} e_{l}(X_{j}) + e_{l}(X_{2}) \sum_{k=3}^{N} e_{m}(X_{k}) + \left\{\sum_{j=3}^{N} e_{l}(X_{j})\right\} \left\{\sum_{k=3}^{N} e_{m}(X_{k})\right\}.$$
(2.12)

Hence,

$$E\left\{\left(\sum_{\substack{j=1\\j\neq 1}}^{N} e_{l}(X_{j})\right)\left(\sum_{\substack{k=1\\k\neq 2}}^{N} e_{m}(X_{k})\right) \middle| (X_{i}, Y_{i}), i = 1, 2\right\}$$

$$= e_{l}(X_{2}) e_{m}(X_{1}) + e_{m}(X_{j})(N-2) a_{l} + e_{l}(X_{2})(N-2) a_{m} + \sum_{j,k=3}^{N} E\left[e_{l}(X_{j}) e_{m}(X_{k})\right]$$

$$= e_{l}(X_{2}) e_{m}(X_{1}) + e_{m}(X_{1})(N-2) a_{l} + e_{l}(X_{2})(N-2) a_{m} + \sum_{j=3}^{N} E\left[e_{l}(X_{j}) e_{m}(X_{j})\right]$$

$$+ \sum_{\substack{j=1\\j\neq k}}^{N} E\left[e_{l}(X_{j})\right] E\left[e_{m}(X_{k})\right]$$

$$= e_{l}(X_{2}) e_{m}(X_{1}) + e_{m}(X_{1})(N-2) a_{l}$$

$$+ e_{l}(X_{2})(N-2) a_{m} + (N-2) E \left[e_{l}(X_{j}) e_{m}(X_{j})\right]$$

$$+ (N-2)(N-3) a_{l} a_{m}$$

$$\equiv I_{2} \quad (\text{say}). \tag{2.13}$$

Hence,

$$(N-1)^{2} I_{1} = E \left[\psi_{l}(X_{1}, Y_{1}) \psi_{m}(X_{2}, Y_{2}) I_{2} \right]$$

$$= E \left[\psi_{l}(X_{1}, Y_{1}) \psi_{m}(X_{2}, Y_{2}) e_{l}(X_{2}) e_{m}(X_{1}) \right]$$

$$+ E \left[\psi_{l}(X_{1}, Y_{1}) \psi_{m}(X_{2}, Y_{2}) e_{m}(X_{1}) \right] (N-2) a_{l}$$

$$+ E \left[\psi_{l}(X_{1}, Y_{1}) \psi_{m}(X_{2}, Y_{2}) e_{l}(X_{2}) \right] (N-2) a_{m}$$

$$+ E \left[\psi_{l}(X_{1}, Y_{1}) \psi_{m}(X_{2}, Y_{2}) \right] (N-2) E \left[e_{l}(X_{j}) e_{m}(X_{j}) \right]$$

$$+ (N-2)(N-3) a_{l} a_{m} E \left[\psi_{l}(X_{1}, Y_{1}) \psi_{m}(X_{2}, Y_{2}) \right]$$

$$= E \left[Y_{1} e'_{l}(X_{1}) Y_{2} e'_{m}(X_{2}) e_{l}(X_{2}) e_{m}(X_{1}) \right]$$

$$+ (N-2) a_{l} E \left[Y_{1} e'_{l}(X_{1}) Y_{2} e'_{m}(X_{2}) e_{l}(X_{2}) \right]$$

$$+ (N-2) E \left[Y_{1} e'_{l}(X_{1}) Y_{2} e'_{m}(X_{2}) \right] E \left[e_{l}(X_{1}) e_{m}(X_{1}) \right]$$

$$+ (N-2) (N-3) a_{l} a_{m} E \left[Y_{1} e'_{l}(X_{1}) \right] E \left[Y_{2} e'_{m}(X_{2}) \right]. \tag{2.14}$$

Let

$$b_{ml} = E[Y_1 e'_l(X_1) e_m(X_1)], \gamma_{lm} = E[Y_1^2 e_l(X_1) e'_m(X_1)], \tag{2.15}$$

$$c_m = E[Y_1 e'_m(X_1)]$$
 (2.16)

and

$$d_{lm} = E[e_l(X_1)e_m(X_1)]. (2.17)$$

Then

$$(N-1)^{2} \operatorname{cov} \left[\psi_{l}(X_{i}, Y_{i}) \eta_{l}(X_{N}^{(i)}), \psi_{m}(X_{j}, Y_{j}) \eta_{m}(X_{N}^{(j)}) \right] = b_{ml} b_{lm} + (N-2) a_{l} b_{ml} c_{m}$$

$$+ (N-2) a_{m} b_{lm} c_{l} + (N-2) c_{l} c_{m} d_{lm}$$

$$+ (N-2)(N-3) a_{l} a_{m} c_{l} c_{m} - a_{l} a_{m} c_{l} c_{m}.$$
 (2.18)

Case (ii): i = j. Then

$$cov \left[\psi_{l}(X_{1}, Y_{1})\eta_{l}(X_{N}^{(1)}), \psi_{m}(X_{1}, Y_{1})\eta_{m}(X_{N}^{(1)})\right]
= E \left[\psi_{l}(X_{1}, Y_{1})\psi_{m}(X_{1}, Y_{1})\eta_{l}(X_{N}^{(1)})\eta_{m}(X_{N}^{(1)})\right]
- E \left[\psi_{l}(X_{1}, Y_{1})\eta_{l}(X_{N}^{(1)})\right] E \left[\psi_{m}(X_{1}, Y_{1})\eta_{m}(X_{N}^{(1)})\right]
= E \left[Y_{1}e'_{l}(X_{1})Y_{1}e'_{m}(X_{1})\eta_{l}(X_{N}^{(1)})\eta_{m}(X_{N}^{(1)})\right]
- a_{l}a_{m}c_{l}c_{m}
= E \left[Y_{1}^{2}e'_{l}(X_{1})e'_{m}(X_{1})\right] E \left[\eta_{l}(X_{N}^{(1)})\eta_{m}(X_{N}^{(1)})\right] - a_{l}a_{m}c_{l}c_{m}
= \gamma_{lm} E \left[\eta_{l}(X_{N}^{(1)})\eta_{m}(X_{N}^{(1)})\right] - a_{l}c_{l}a_{m}c_{m}.$$
(2.19)

Let us now compute

$$(N-1)^{2} E\left[\eta_{l}(X_{N}^{(1)})\eta_{m}(X_{N}^{(1)})\right] = E\left[\left\{\sum_{j=2}^{N} e_{l}(X_{j})\right\} \left\{\sum_{k=2}^{N} e_{m}(X_{k})\right\}\right]$$

$$= \sum_{j=2}^{N} \sum_{k=2}^{N} E\left[e_{l}(X_{j})e_{m}(X_{k})\right]$$

$$= (N-1) E\left[e_{l}(X_{1})e_{m}(X_{1})\right] + (N-1)(N-2) E\left[e_{l}(X_{1})e_{m}(X_{2})\right]$$

$$= (N-1) d_{lm} + (N-1)(N-2) a_{l} a_{m}. \tag{2.20}$$

Hence,

$$\operatorname{cov}\left[\psi_{l}(X_{1}, Y_{1})\eta_{l}(X_{N}^{(1)}), \psi_{m}(X_{1}, Y_{1})\eta_{m}(X_{N}^{(1)})\right] = \gamma_{lm} \left\{ \frac{d_{lm}}{N-1} + \frac{N-2}{N-1} a_{l} a_{m} \right\} - a_{l} c_{l} a_{m} c_{m}. \tag{2.21}$$

Calculations made above in the cases (i) and (ii) lead to the formula

$$\operatorname{var}\left[\hat{\delta}_{N}\right] = \frac{4}{N^{2}} \sum_{l=1}^{q(N)} \sum_{m=1}^{q(N)} \left[\gamma_{lm} \left\{ \frac{d_{lm}}{N-1} + \frac{N-2}{N-1} a_{l} a_{m} \right\} - a_{l} c_{l} a_{m} c_{m} \right] N$$

$$+ \frac{4}{N^{2}} \sum_{l=1}^{q(N)} \sum_{m=1}^{q(N)} \left\{ \begin{array}{l} \frac{b_{ml}b_{lm}}{(N-1)^{2}} + \frac{N-2}{(N-1)^{2}} a_{l}b_{ml}c_{m} \\ + \frac{N-2}{(N-1)^{2}} a_{m}b_{lm}c_{l} \\ + \frac{N-2}{(N-1)^{2}} c_{l}c_{m}d_{lm} \\ + \frac{(N-2)(N-3)}{(N-1)^{2}} a_{l}a_{m}c_{l}c_{m} \end{array} \right\} N(N-1)$$

$$(2.22)$$

$$= \frac{4}{N(N-1)} \sum_{l=1}^{q(N)} \sum_{m=1}^{q(N)} \gamma_{lm} d_{lm} + \frac{4(N-2)}{N(N-1)} \sum_{l=1}^{q(N)} \sum_{m=1}^{q(N)} \gamma_{lm} a_{l} a_{m}
- \frac{4}{N} \left(\sum_{l=1}^{q(N)} a_{l} c_{l}\right)^{2} + \frac{4N(N-1)}{N^{2}(N-1)^{2}} \sum_{l=1}^{q(N)} \sum_{m=1}^{q(N)} b_{ml} b_{lm}
+ \frac{4N(N-1)(N-2)}{N^{2}(N-1)^{2}} \sum_{l=1}^{q(N)} \sum_{m=1}^{q(N)} a_{l} b_{ml} c_{m} + \frac{4N(N-1)(N-2)}{N^{2}(N-1)^{2}} \sum_{l=1}^{q(N)} \sum_{m=1}^{q(N)} a_{m} b_{lm} c_{ml}
+ \frac{4N(N-1)(N-2)}{N^{2}(N-1)^{2}} \sum_{l=1}^{q(N)} \sum_{m=1}^{q(N)} c_{l} c_{m} d_{lm}
+ \frac{4N(N-1)(N-2)(N-3)}{N^{2}(N-1)^{2}} \sum_{l=1}^{q(N)} \sum_{m=1}^{q(N)} a_{l} a_{m} c_{l} c_{m}
- \frac{4N(N-1)}{N^{2}} \sum_{l=1}^{q(N)} \sum_{m=1}^{q(N)} a_{l} a_{m} c_{l} c_{m}.$$
(2.23)

Note that

$$\sup_{l,m} v_{lm} < \infty, \quad \sup_{l,m} b_{ml} < \infty, \quad \sup_{l} a_{l} < \infty, \quad \sup_{l} c_{l} < \infty \tag{2.24}$$

and

$$\sup_{l,m} d_{lm} < \infty \tag{2.25}$$

by assumption (A2)(iii). Observe that the coefficient of $(\sum_{i=1}^{q(N)} a_i c_i)^2$ in the expression for $var(\hat{\delta}_N)$ is

$$-\frac{4}{N} + \frac{4(N-2)(N-3)}{N(N-1)} - \frac{4(N-1)}{N} = \frac{4(6-4N)}{N(N-1)}$$
$$\simeq \frac{-16}{N} + 0\left(\frac{1}{N}\right).$$

Under the assumption (A3), it follows that

$$\operatorname{var}(\hat{\delta}_N) \simeq O\left(\frac{q^2(N)}{N^2} + \frac{q^2(N)}{N}\right). \tag{2.26}$$

Theorem. Under assumptions (A1) and (A2), if $q(N) \rightarrow \infty$ such that

$$\frac{q^2(N)}{N} \to 0 \quad \text{as } N \to \infty \tag{2.27}$$

and $EY^2 < \infty$, then

$$\hat{\delta}_N \stackrel{\mathsf{p}}{\to} \delta \quad \text{as } N \to \infty.$$
 (2.28)

Proof. The result follows from the fact

$$\operatorname{var}(\hat{\delta}_N) \to 0$$
 and $E(\hat{\delta}_n) \to \delta$ as $n \to \infty$.

3. Remarks

Let us now discuss the limiting behaviour of

$$\{\hat{\delta_N} - E(\hat{\delta}_N)\}$$
 (3.1)

if any. Note that

$$\begin{split} \{\hat{\delta_{N}} - E(\hat{\delta}_{N})\} &= -\frac{2}{N} \sum_{i=1}^{N} \left[Y_{i} \frac{\partial \hat{f_{N_{i}}}}{\partial X} \Big|_{X=x_{i}} - E\left(Y_{i} \frac{\partial \hat{f_{N_{i}}}}{\partial X} \Big|_{X=x_{i}} \right) \right] \\ &= -\frac{2}{N} \sum_{l=1}^{q(N)} \sum_{i=1}^{N} \left\{ \psi_{l}(X_{i}, Y_{i}) \eta_{l}(X_{N}^{(i)}) - E(\psi_{l}(X_{i}, Y_{i}) \eta_{l}(X_{N}^{(i)})) \right\} \\ &= -\frac{2}{N} \sum_{i=1}^{N} \left[\sum_{l=1}^{q(N)} \left\{ \psi_{l}(X_{i}, Y_{i}) \eta_{l}(X_{N}^{(i)}) - E\left[\psi_{l}(X_{i}, Y_{i}) \eta_{l}(X_{N}^{(i)}) \right] \right\} \right] \\ &= -\frac{2}{N} \sum_{i=1}^{N} Z_{Ni}, \end{split}$$

where

$$Z_{Ni} = [\psi_1(X_i, Y_i)\eta_1(X_N^{(i)}) + \dots + \psi_{q(N)}(X_i, Y_i)\eta_{q(N)}(X_N^{(i)})]$$
$$- E\{[\psi_1(X_i, Y_i)\eta_1(X_N^{(i)}) + \dots + \psi_{q(N)}(X_i, Y_i)\eta_{q(N)}(X_N^{(i)})]\}.$$

Note that

$$\{Z_{Ni}, 1 \leq i \leq N\}$$

are finitely interchangeable for each N. Furthermore $E(Z_{Ni}) = 0$.

From the structure of $\{Z_{Ni}, 1 \le i \le N, N \ge 1\}$, it should be possible to study the asymptotic behaviour of the estimator $\hat{\delta}_N$. However, the limit theorems for exchangeable arrays presently available do not seem to be applicable in this context. The problem remains open.

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